



# **Towards Action Representation based on Acoustic Packages**

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- **Cues for action segmentation in tutoring situations**
  - Background on Acoustic Packaging [Brand et al., 2007]
  - Computational Model of Acoustic Packaging and Evaluation
- **Action Learning in infants**
  - Inferences about other's goals [Gergeley, 2003]
- **AP for learning and representing actions**

## How to associate information in different modalities for language and action learning?

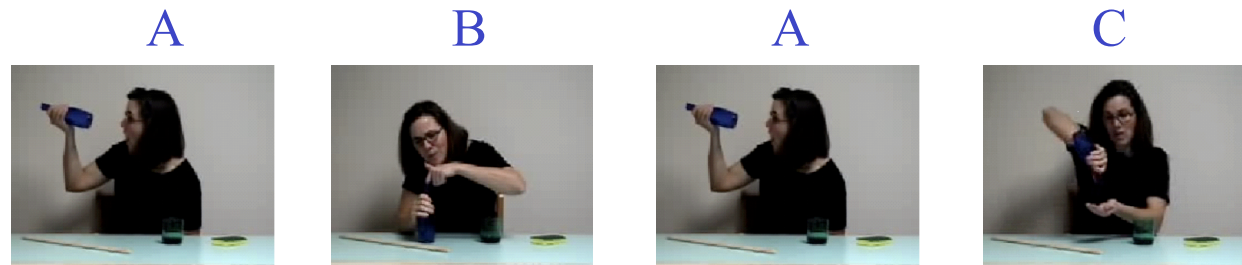
- **Synchrony** [Zukow-Goldring, 1997] [Matatyaho, Mason & Gogate et al., 2007]
  - Synchronous object movement and verbal labeling enhances object learning
  - More low-level synchrony in ACI than in AAI [Rolf et al., 2009]
- **Acoustic Packaging** [Brand et al, 2007]
  - Synchrony between language and events helps to divide sequence of events into units [Hirsh-Pasek & Golinkoff, 1996]
  - Speech segment determines perceived (end of) action

**Question:** Does speech influence how action is structured by infants?

**Experiment:** 32 Infants of 7.5 – 11.5 months of age; Preferential Looking

**Familiarization**

Video

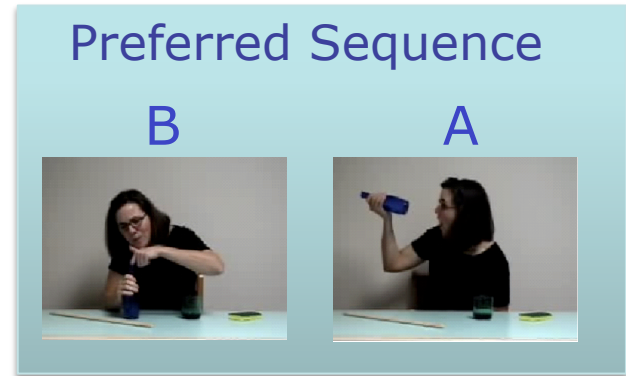


Audio

~~Wow! Do you see what she's doing? She's blixing!~~

**Test: Split Screen**

Video



Non-packaged sequence perceived as new  
 ⇒ **Speech structures action !**

## Long term goals

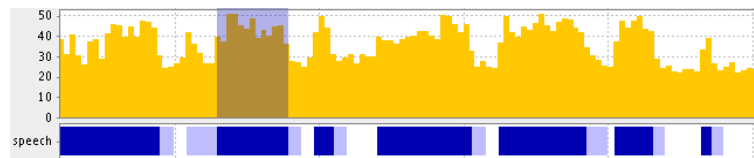
- Temporal segmentation of actions
- Generating appropriate feedback
- Integration with action and speech learning approaches

## Evaluation

- Does model reflect structural properties of tutoring behavior?

## Segmentation

Speech: by ASR (ESMERALDA)

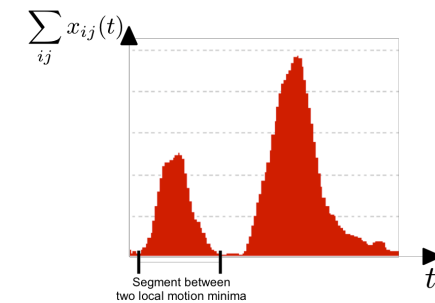


Action: by motion history images

Motion History Image

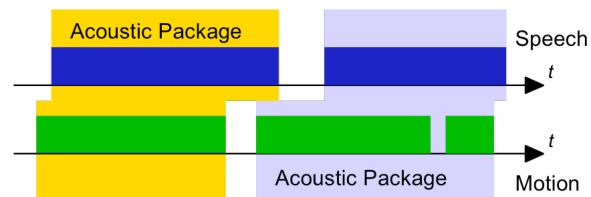


Amount of Motion per Frame

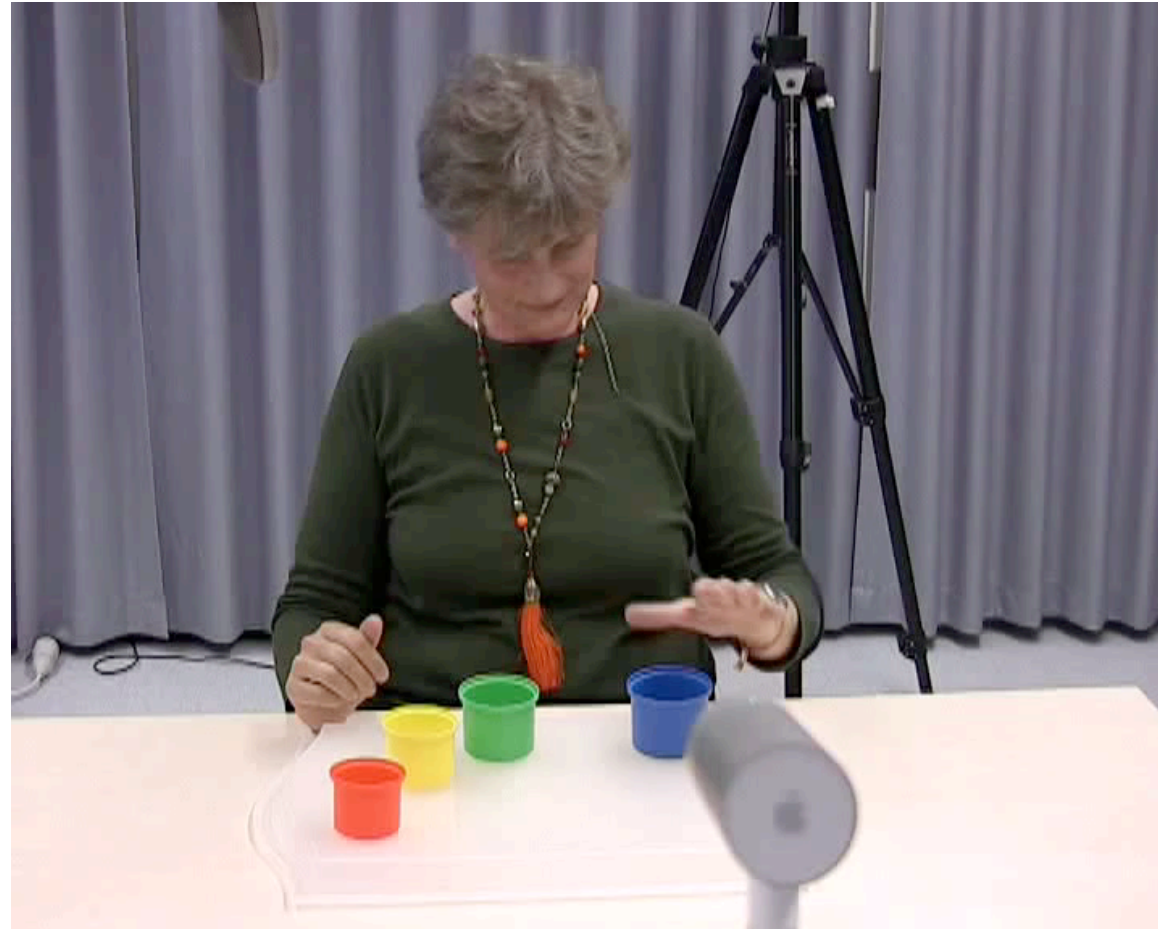


## Temporal Association

Acoustic Package created if segments overlap











## Data

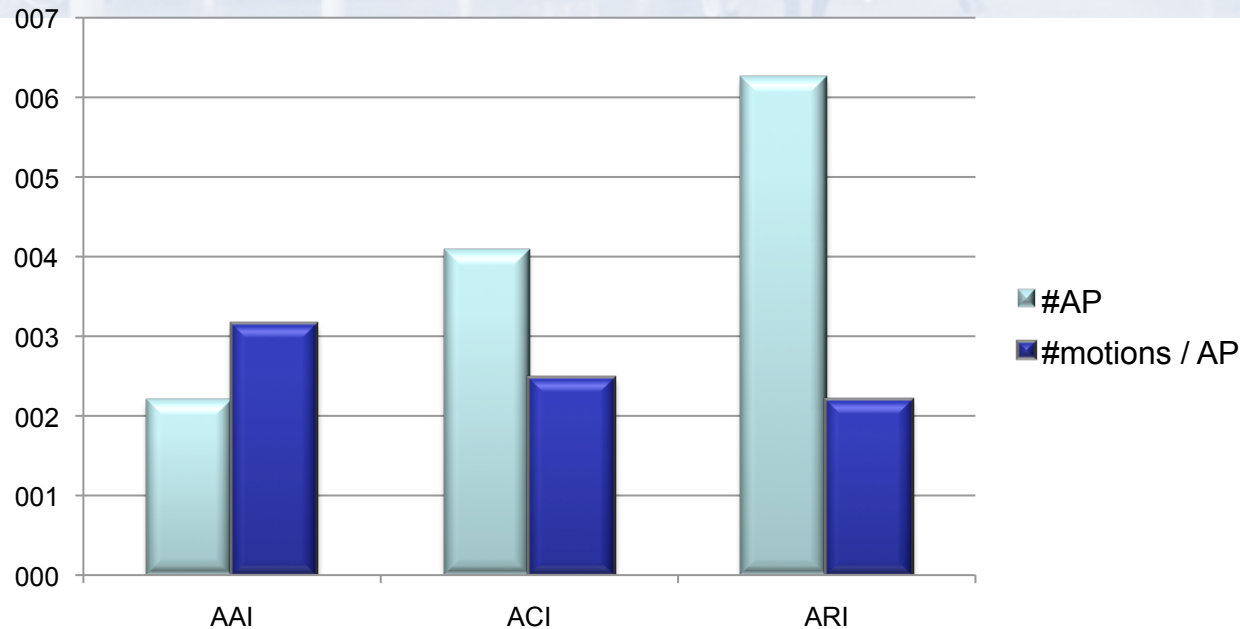
- Videos from Motionese corpus (11 AAI, 11 ACI) and from babyface study (11 ARI)
- Task: stacking cups

## Analysis

- Automatic detection of Acoustic Packages
- Measurements:
  - number of Acoustic Packages (#AP)
  - mean number of motions per Acoustic Package (#motions / AP)

## Hypothesis

- ACI more structured than AAI
- More #AP and less #motions / AP in ACI



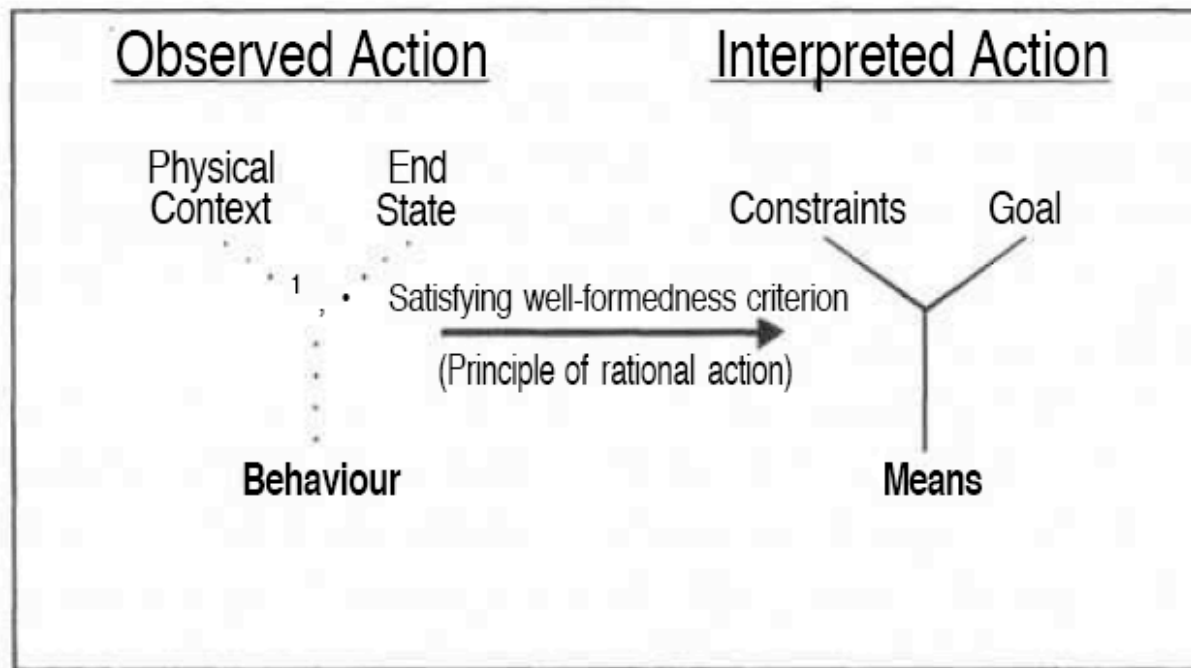
- Sig. more Acoustic Packages in ACI and ARI
  - Sig. less Motions per Acoustic Packages in ACI and ARI
- ⇒ Hypothesis confirmed
- ⇒ Automatically detected Acoustic Packages find more structure in ACI and ARI
- ⇒ Acoustic Packages as basis for Action Representation?



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## How to draw inferences about other's goal directed actions?

[Gergeley, 2003]



Assumption (well-formedness criterion):

Observed behavior

– will bring about goal state

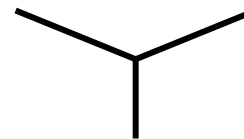
– is most efficient means to reach goal

## Support for Interpreting Action in IDS



Constraints

Goal



Means



**Top-down processes: Language (syntactical constructions) can help to determine goal of action (e.g. path vs goal-oriented)**

### **Goal-oriented**

- „look the frog jumps **to the leave**“
- „look the yellow cup goes **into the red one**“

### **Path-oriented**

- „look how the frog **jumps**“
- „look how you can **turn** the cup upside down“



Interaction can help to determine goal of action (e.g. path vs goal-oriented) – Hypothesis!

## Goal-oriented

- Tutor: „look the frog jumps **to the leave**“
- (Infant lets the frog jump around)
- Tutor: „no no, the frog wants to go **to the leave**“

## Path-oriented

- Tutor: „look how the frog **jumps**“
- (infant moves frog to the leave)
- Tutor: „no, it doesn't go like this, look how it **jumps**“



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## Discussion – Acoustic Packages

- Acoustic Packages as a learner-oriented **segmentation** of the action
- Multi-modal binding
  - AP contain specifically chunked structure (tying verbal constructions to visual movements or series of movements)
- Interaction
  - AP segmentation will differ depending on learner feedback

## Discussion - Representation

- Multi-modal:
  - Verbal (lexical, syntactic constructions) (interpretation of observed behavior)
  - Visual (e.g. scene changes -> end state -> goal(s))
  - Trajectories (e.g. hand movements -> physical context -> constraints; hand movements -> behavior -> means)
  - Multi-modal structure (means, constraints, goal(s))
- Dynamic in nature:
  - Representation will change over duration of interaction
  - Representation will change over different interactions (and learning of other actions)



Thank you for your attention!